



## Manifolds - Part 29

$M$  smooth manifold of dimension  $n \Rightarrow T_p M$   $n$ -dimensional vector space

Definition:

$$\omega : M \longrightarrow \bigcup_{p \in M} \text{Alt}^k(T_p M)$$

$$p \longmapsto \omega_p = \omega(p) \in \text{Alt}^k(T_p M)$$

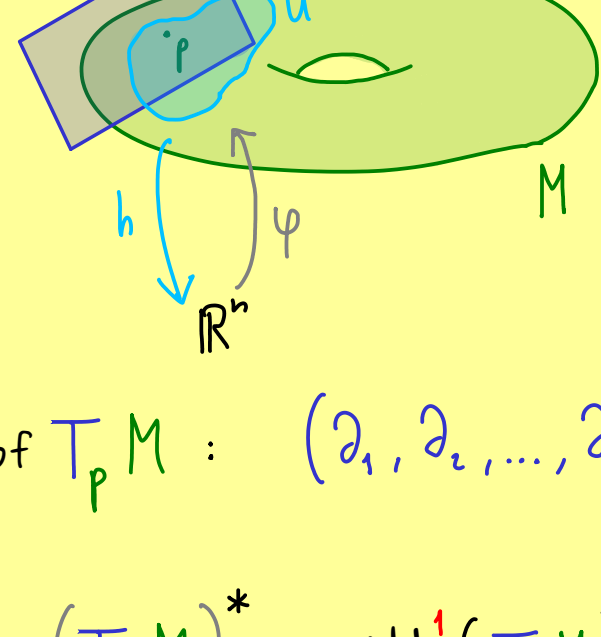
is called a  $k$ -form on  $M$ .

We also define:  $\omega \wedge \eta$  as  $(\omega \wedge \eta)(p) := \omega(p) \wedge \eta(p)$

$$f^* \omega \text{ as } (f^* \omega)(p) := (df_p)^* \omega(f(p))$$

$f : N \rightarrow M$  smooth

Basis elements:



basis of  $T_p M$  :  $(\partial_1, \partial_2, \dots, \partial_n)$  with  $\partial_j := \varphi_*(e_j) = d\varphi_{h(p)}(e_j)$

basis of  $(T_p M)^* = \text{Alt}^1(T_p M)$  :  $(dx_p^1, dx_p^2, \dots, dx_p^n)$

$$\text{defined by: } dx_p^j(\partial_k) = \delta_k^j = \begin{cases} 1, & j=k \\ 0, & j \neq k \end{cases}$$

Proposition: A basis of  $\text{Alt}^k(T_p M)$  is given by:

$$(dx_p^{\mu_1} \wedge dx_p^{\mu_2} \wedge \dots \wedge dx_p^{\mu_k})_{\mu_1 < \mu_2 < \dots < \mu_k}$$

Example:  $\dim(M) = 3$ ,  $\text{Alt}^2(T_p M)$  :

$$(dx_p^1 \wedge dx_p^2, dx_p^1 \wedge dx_p^3, dx_p^2 \wedge dx_p^3)$$

Conclusion: Each  $k$ -form on  $M$  can locally be written as:

$$\omega(p) = \sum_{\mu_1 < \dots < \mu_k} \omega_{\mu_1, \mu_2, \dots, \mu_k}(p) \cdot dx_p^{\mu_1} \wedge dx_p^{\mu_2} \wedge \dots \wedge dx_p^{\mu_k}$$

$$\omega_{\mu_1, \mu_2, \dots, \mu_k} : U \rightarrow \mathbb{R} \text{ component functions}$$

Definition: • If all component functions are differentiable at  $p$ ,

then  $\omega$  is differentiable at  $p$ .

• If  $\omega$  is differentiable at all  $p \in M$ ,

then  $\omega$  is called a differential form on  $M$ .

$$\omega \in \Omega^k(M)$$

$$\Omega^0(M) := C^\infty(M)$$