



Ordinary Differential Equations - Part 2

Definitions: For $I \subseteq \mathbb{R}$ (interval, open set, union intervals,...)

$$C^k(I) := \left\{ x: I \rightarrow \mathbb{R} \mid \underbrace{x \text{ is } k\text{-times continuously differentiable}}_{\substack{\dot{x}, \ddot{x}, \dots, x^{(k)} \text{ continuous functions} \\ \dot{x} = \frac{dx}{dt}}} \right\}$$

Ordinary differential equation: $F(t, x, \dot{x}, \dots, x^{(k)}) = 0$

→ ODE

continuous

Example: $t + x + 2\dot{x} + (\ddot{x})^2 = 0$

(explicit) ODE of order 1: $\dot{x} = w(t, x), w: I \times J \rightarrow \mathbb{R}, I, J \subseteq \mathbb{R}$
intervals

Example: $\dot{x} = x + t$

What about? $\begin{pmatrix} \dot{x}_1 = x_2 + t \\ \dot{x}_2 = x_1 + t \end{pmatrix} \rightsquigarrow \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = w\left(t, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right)$

System of (explicit) ODEs of order 1:

$$\dot{x} = w(t, x), \quad x(t) \in \mathbb{R}^n, \quad w: I \times U \rightarrow \mathbb{R}^n$$

↑ open set in \mathbb{R}^n

solution of ODE: $\alpha: (t_0, t_1) \rightarrow U$ with $(t_0, t_1) \subseteq I$

satisfies $\dot{\alpha}(t) = w(t, \alpha(t))$ for all $t \in (t_0, t_1)$.

Example: $\begin{pmatrix} \dot{x}_1 = x_2 \\ \dot{x}_2 = -x_1 \end{pmatrix}, n=2, U = \mathbb{R}^2, w(t, x) = \begin{pmatrix} x_2 \\ -x_1 \end{pmatrix}$

$\rightsquigarrow \alpha(t) = \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix}$ is a solution

$\tilde{\alpha}(t) = \frac{1}{2} \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix}$ is a solution

