

Ordinary Differential Equations - Part 19

System of linear differential equations: (of first order) $\dot{x} = A(t) \times + b(t) \quad \text{with} \qquad I \ni t \bigoplus_{\text{continuous}} A(t) \in \mathbb{R}^{h \times n}$ $I \ni t \longmapsto_{h \setminus I} \otimes b(t) \in \mathbb{R}^{h}$ • solutions are global $\alpha : I \rightarrow \mathbb{R}^{n}$ • autonomous systems: A(t) = A, b(t) = b $e \times ample: A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, b = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $V(x) = A_X + b$ • corresponding homogeneous system $\dot{x} = A(t) \times$ Fact: If $\alpha : I \rightarrow \mathbb{R}^{n}$, $\beta : I \rightarrow \mathbb{R}^{n}$ are two solutions of $\dot{x} = A(t) \times J$

$$\begin{aligned} &(\alpha + \beta)(t) = \dot{\alpha}(t) + \dot{\beta}(t) = A(t)\alpha(t) + A(t)\beta(t) \\ &= A(t)(\alpha(t) + \beta(t)) \end{aligned}$$

linear combinations of solutions $(\lambda \cdot \alpha)(t) = A(t)(\lambda \cdot \alpha(t))$ are solutions

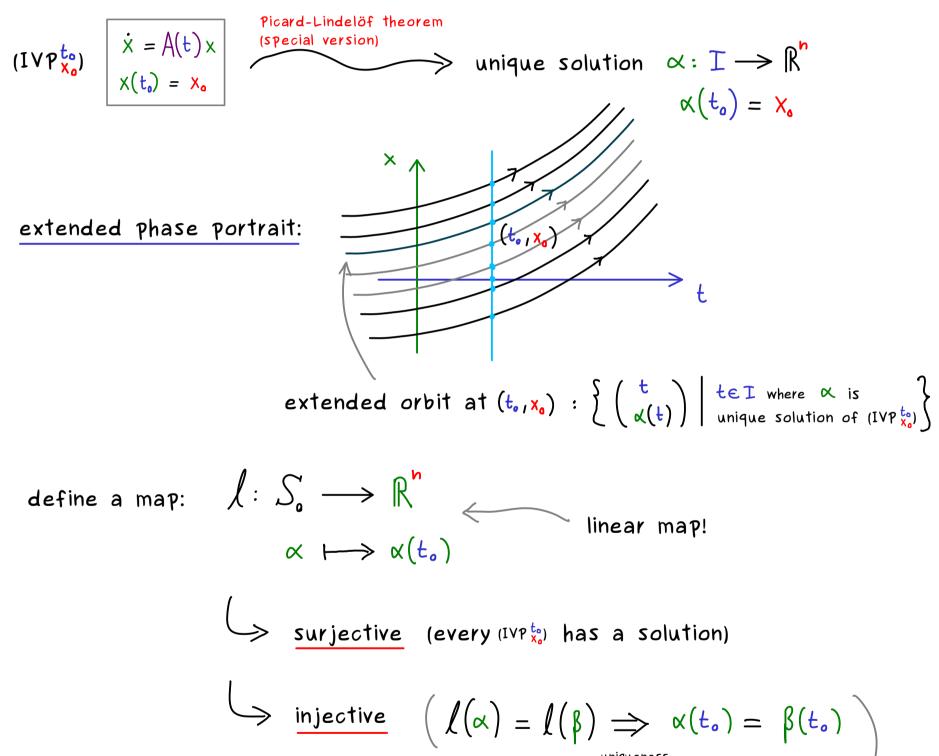
<u>Proposition:</u> The solution set of the corresponding homogeneous system

$$S_{\mathbf{a}} := \left\{ \boldsymbol{\alpha} : \mathbf{I} \longrightarrow \boldsymbol{\mathbb{R}}^{\mathbf{h}}_{\text{differentiable}} \mid \dot{\boldsymbol{\alpha}}(t) = \boldsymbol{A}(t) \boldsymbol{\alpha}(t) \quad \substack{\text{for all} \\ t \in \mathbf{I}} \right\}$$

forms an n-dimensional R-vector space.

Proof:
$$S_0$$
 is a subspace in the R-vector space $C^1(I, R^n)$.

What about the dimension of S_0^2 .



$$\implies$$
 $\alpha = \beta$ on 1

$$\implies l: S_{a} \longrightarrow \mathbb{R}^{h}$$
 isomorphism

$$\implies$$
 dim(S₀) = dim(Rⁿ) = r